

**USEFUL EQUATIONS**

$$\sigma_{avg} = \frac{F_N}{A}$$

$$\tau_{avg} = \frac{V}{A}$$

**Generalized Hooke's Law**

$$\varepsilon_x = \left(\frac{1}{E}\right) [\sigma_x - \nu(\sigma_y + \sigma_z)] + \alpha\Delta T$$

$$\varepsilon_y = \left(\frac{1}{E}\right) [\sigma_y - \nu(\sigma_x + \sigma_z)] + \alpha\Delta T$$

$$\varepsilon_z = \left(\frac{1}{E}\right) [\sigma_z - \nu(\sigma_x + \sigma_y)] + \alpha\Delta T$$

$$\gamma_{xy} = \left(\frac{1}{G}\right) \tau_{xy} \quad \gamma_{xz} = \left(\frac{1}{G}\right) \tau_{xz} \quad \gamma_{yz} = \left(\frac{1}{G}\right) \tau_{yz}$$

$$G = \frac{E}{2(1+\nu)}$$

**Axial Deformations**

$$e_{AB} = u_B - u_A \quad e = \int_0^L \frac{F(x)}{E(x)A(x)} dx + \int_0^L \alpha\Delta T dx \quad e = \frac{FL}{EA} + \alpha\Delta TL$$

$$e = u \cos(\theta) + v \sin(\theta)$$

**Torsional Deformations**

$$\phi_{AB} = \phi_B - \phi_A \quad \phi = \int_0^L \frac{T(x)}{G(x)I_p(x)} dx \quad \phi = \frac{TL}{GI_p}$$

$$\gamma = \rho \frac{d\phi}{dx} \quad \tau = G\rho \frac{d\phi}{dx} \quad \gamma = \frac{T\rho}{GI_p} \quad \tau = \frac{T\rho}{I_p}$$

with  $I_p = \int_A \rho^2 dA$        $I_p = \frac{\pi r^4}{2}$  (solid)       $I_p = \frac{\pi}{2}(r_o^4 - r_i^4)$  (hollow)

**Flexural and Shear Stress**

$$\sigma(x, y) = -\frac{Ey}{\rho} = -\frac{M_{zz}y}{I_{zz}} \quad I_{zz} = \frac{bh^3}{12} \text{ (rectangle)} \quad I_{zz} = \frac{\pi}{4}R^4 \text{ (circle)}$$

$$\tau(x, y) = \frac{VQ}{I_{zz}t} = \frac{VA^*y^*}{I_{zz}t} \quad I_{zz} = \frac{bh^3}{36} \text{ (triangle)} \quad I_{zz} = \left(\frac{\pi}{8} - \frac{8}{9\pi}\right)R^4 \text{ (semi-circle)}$$

$$\tau_{max} = \frac{3V}{2A} \text{ (rectangle)}$$

$$\tau_{max} = \frac{4V}{3A} \text{ (circle)}$$

